



# Mobile SLAM **COLOR**

## 3D Laser Scanner

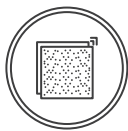


Surveying  
& Mapping

World-Realistic Color · Precision Level (cm)  
Rotating Single Lidar

## R8-Surveying & Mapping · World-Realistic Color · Precision Level (cm)

R8 is a tool that can be handheld, wearable, and vehicle-on which allows to be widely used in various fields, such as real 3D, topographic mapping, water conservancy surveys, completion surveys, traffic surveys, mine surveys, facade surveys, underground space mapping, power inspections, and forestry surveys, etc.



2cm  
Repeatability Accuracy



RTK-SLAM  
PPK-SLAM



0.015°  
Horizontal &  
Vertical Accuracy Error



Accuracy Report &  
GCP Inserting Instruction



### PARAMETER

|   |                                  |  |   |
|---|----------------------------------|--|---|
| Relative Accuracy <sup>1</sup>                    | 1cm                              | Movable Objects Removal                | √ |
| Absolute Accuracy <sup>2</sup>                    | Horizontal 1.8cm, Vertical 2.5cm | CORS System                            | √ |
| 5A Criteria of Surveying and Mapping <sup>3</sup> | √                                | LIO-PANO <sup>6</sup>                  | √ |
| Repeatability Accuracy <sup>4</sup>               | 2cm                              | RTK-SLAM <sup>7</sup>                  | √ |
| Horizontal/Vertical Accuracy Error                | 0.015°                           | PPK-SLAM <sup>8</sup>                  | √ |
| Point Cloud Density <sup>5</sup>                  | 10,000 pts/m <sup>2</sup>        | LiRF                                   | × |
| Point Cloud Thickness                             | 1cm                              | 3D Real Scene Mesh Models              | × |
| Imager Sensor                                     | 1inch SONY CMOS*2                | 3D Thermal Map of Point Cloud Accuracy | √ |
| Camera Field of View                              | 360°                             | Accuracy Report                        | √ |
| Lens  | Leica F2.2*2                     | GCP Inserting Instruction              | √ |

| MODEL             | R8-16   | R8-32/300 |
|-------------------|---------|-----------|
| Laser Channels    | 16      | 32        |
| Measure Range     | 120m    | 120m/300m |
| Points per Second | 320,000 | 640,000   |

1/2/4. Scenes with weak quantity and quality can impact Repeatability Accuracy, Relative Accuracy, and Absolute Accuracy, it's better to acquire the accurate point cloud results according to the working methods which are recommended by the manufacturer.

3. 5A Criteria of Surveying and Mapping: In the geospatial information, anyone, at any time, using any device, following any route, and scanning any scene, can obtain the unique result of point clouds.

5. Point Cloud Density: Products can approach to the maximum density of point clouds.

6. LIO-PANO: Online colorization technology with multi-model fusion of lidar and panoramic camera.

7. RTK-SLAM: Tightly coupled complementary filtering algorithm of Real-Time Kinematic.

8. PPK-SLAM: Tightly coupled complementary filtering algorithm of Post-Processed Kinematic.

9. LiRF: Lidar Radiance Fields.

